

lisa pathfinder

Ira Thorpe, NASA/GSFC On behalf of the LPF Team NASA Advisory Council Astrophysics Subcommittee Meeting Washington, DC March 16th, 2016

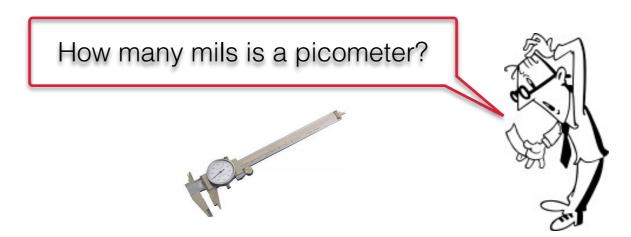
Why LISA Pathfinder?



10⁻¹² = 0.000000000001

Picophobia (paikoʊ-fōbēə) 1. (*noun*) Extreme or irrational fear of large negative exponents, especially when related to engineering requirements.

(origins: Spanish, Greek)



Picophobia for LISA

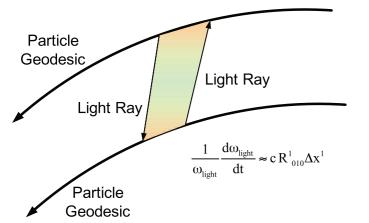


- Acceleration noise: ~3x10⁻¹⁵ m/s²/Hz^{1/2} @ 1mHz
- Distance measurement: ~7x10⁻¹² m/Hz^{1/2} @ 1mHz
- received light power: ~10⁻¹⁰ W
- temperature stability: ~10⁻⁶ K/Hz^{1/2} @ 1mHz
- pointing requirement: ~8x10⁻⁹ rad/Hz^{1/2} @ 1mHz

Solution: Fly a Tech Demo



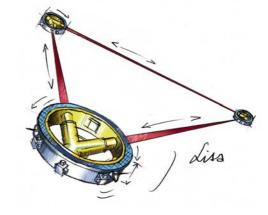
Textbook GW detector



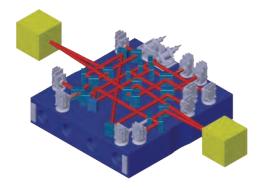
Measure curvature by timing photon travel between freely-falling objects

freely-falling objects \rightarrow drag-free test masses photon timing \rightarrow heterodyne interferometry multiple arms \rightarrow noise rejection, improved signal

LISA-like mission



Technology Demonstrator

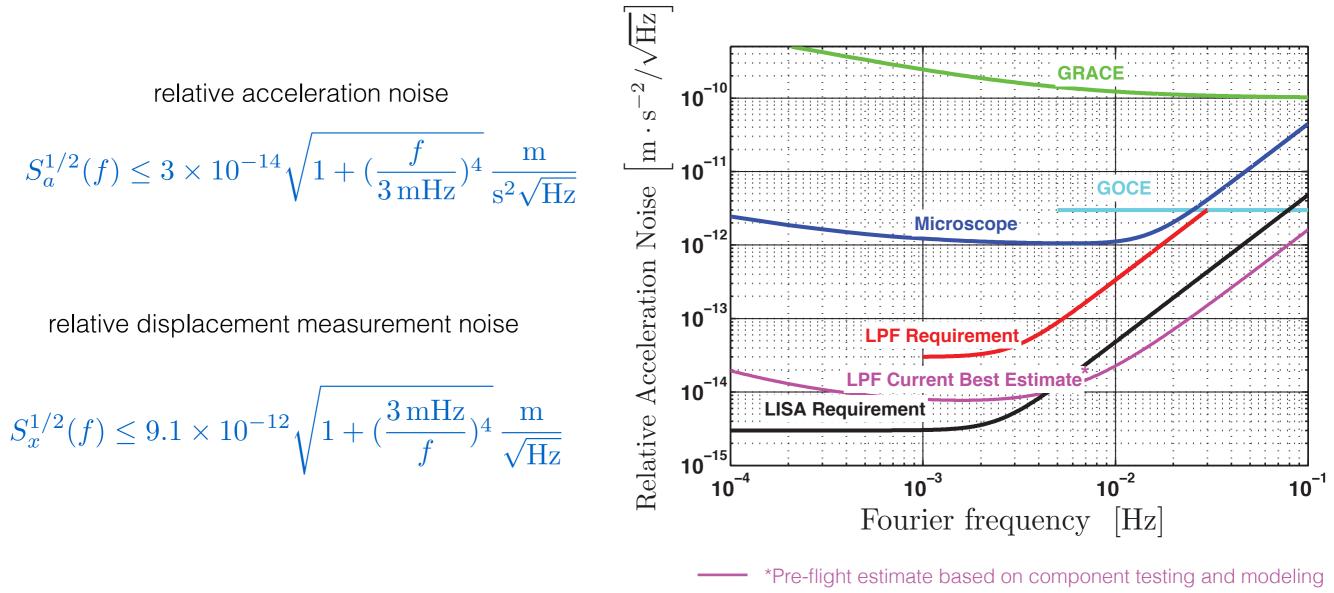


Single LISA arm reduced to fit on one spacecraft GW signal vanishes Instrument Noise remains

LPF Goals



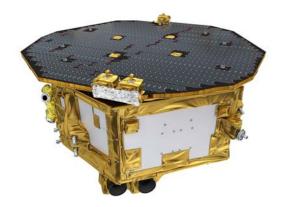






Key Components







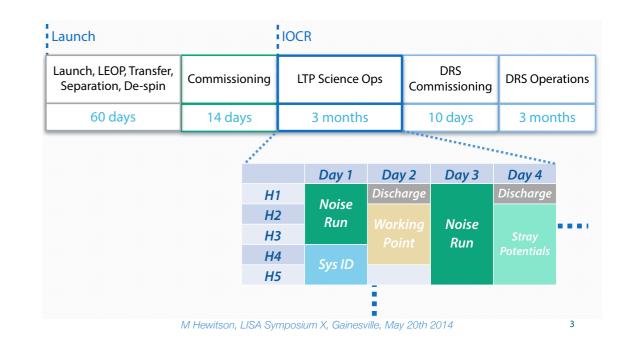


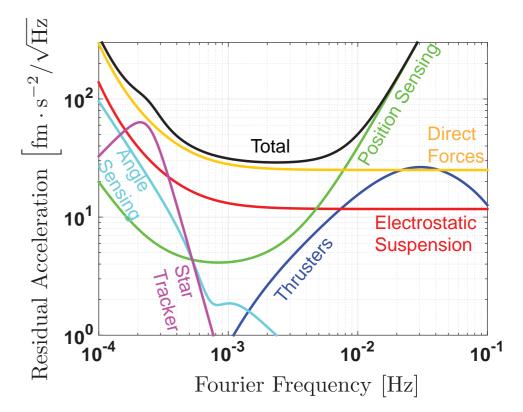
- Spacecraft (ESA)
 - Micronewton thrusters (cold gas)
 - Drag-free control laws
 - Emphasis on mechanical, thermal, & gravitational stability
- LISA Technology Package (ESA & European Consortium)
 - Two gravitational reference sensors
 - Optical Metrology System
 - Thermal/Magnetic Diagnostic System
- ST7-DRS (NASA/JPL)
 - Micronewton thrusters (colloidal)
 - Drag-free control laws (use LTP sensors/actuators)

Operations



- Industrial Commissioning, LTP Operations, ST7 Operations, Extended Mission?
- Goal: physics-based model for the residual acceleration noise
- Operations are a series of experiments to measure various couplings/noise contributions/etc.
- Data analysis must be rapid & accurate to optimize planning for the remaining mission timeline





Schedule of Events (nominal)



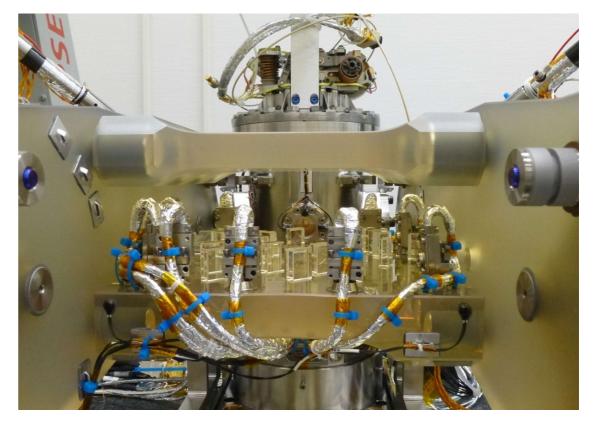
Dec 7-11: Apogee-raising burns Dec 12: Trajectory trim Dec 17-20: Cold Gas Thruster Commissioning Jan. 2-10: CMNT Commissioning Jan. 11: LTP Commissioning Begins Jan 22: Propulsion module separation Feb 3: Test Mass De-cage (launch lock) Feb 15/16: Test Mass release (electrostatic control) Feb 29: LTP Commissioning Ends Mar. 7th: In-Orbit Commissioning Review Passed Mar-June: LTP Operations Late June: DRS Commissioning June-Sept: DRS Operations

Extended Mission / Joint Operations ?

I&T and Launch Campaign Highlights



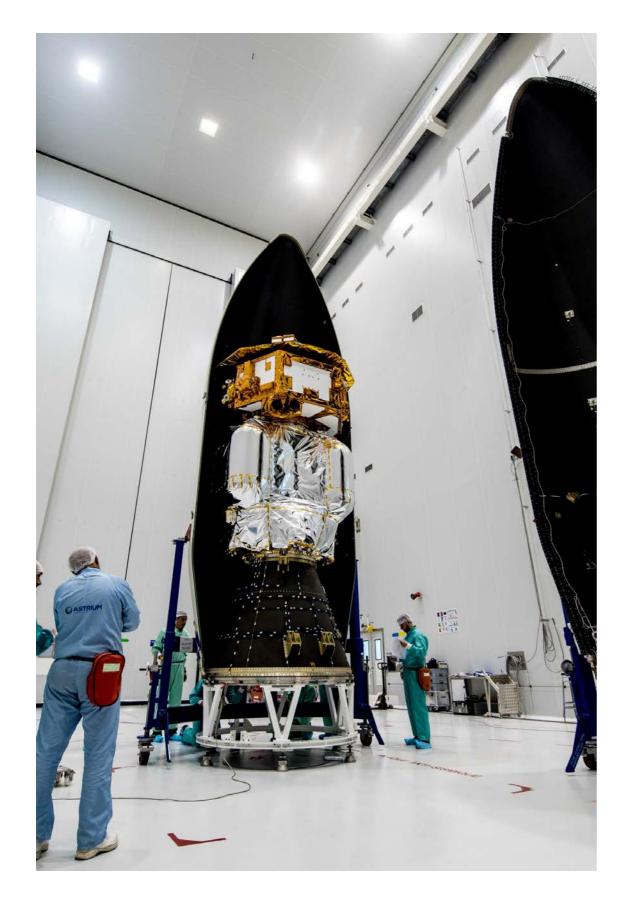






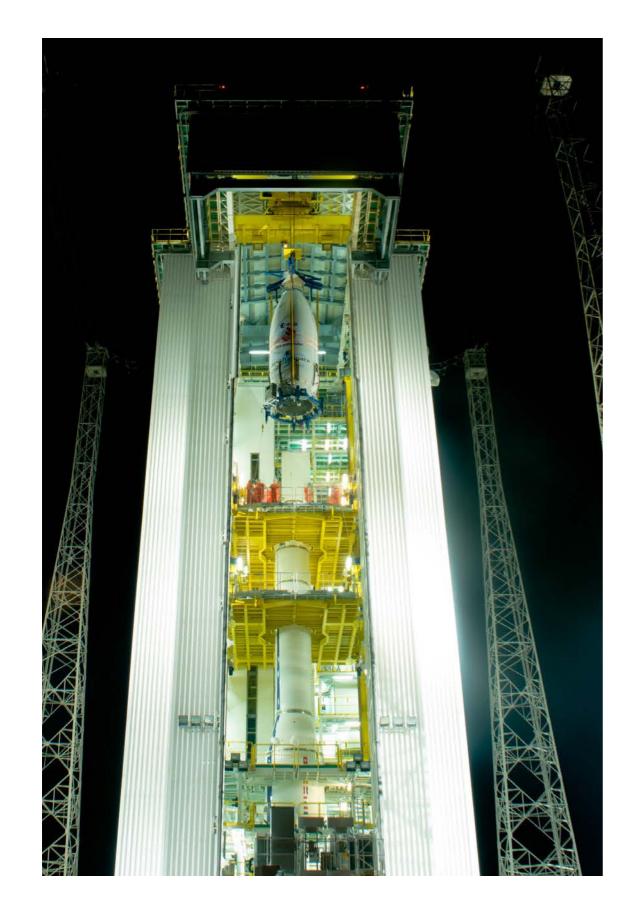




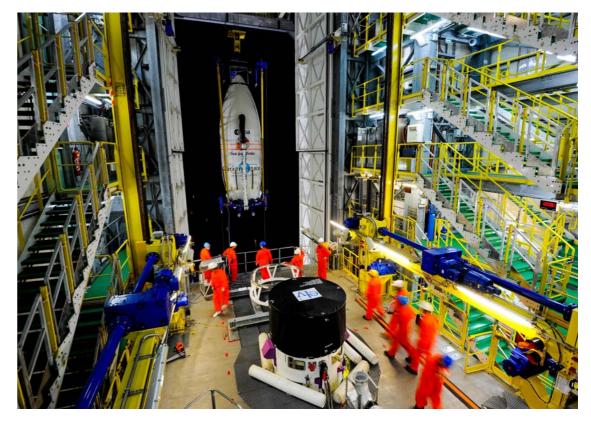








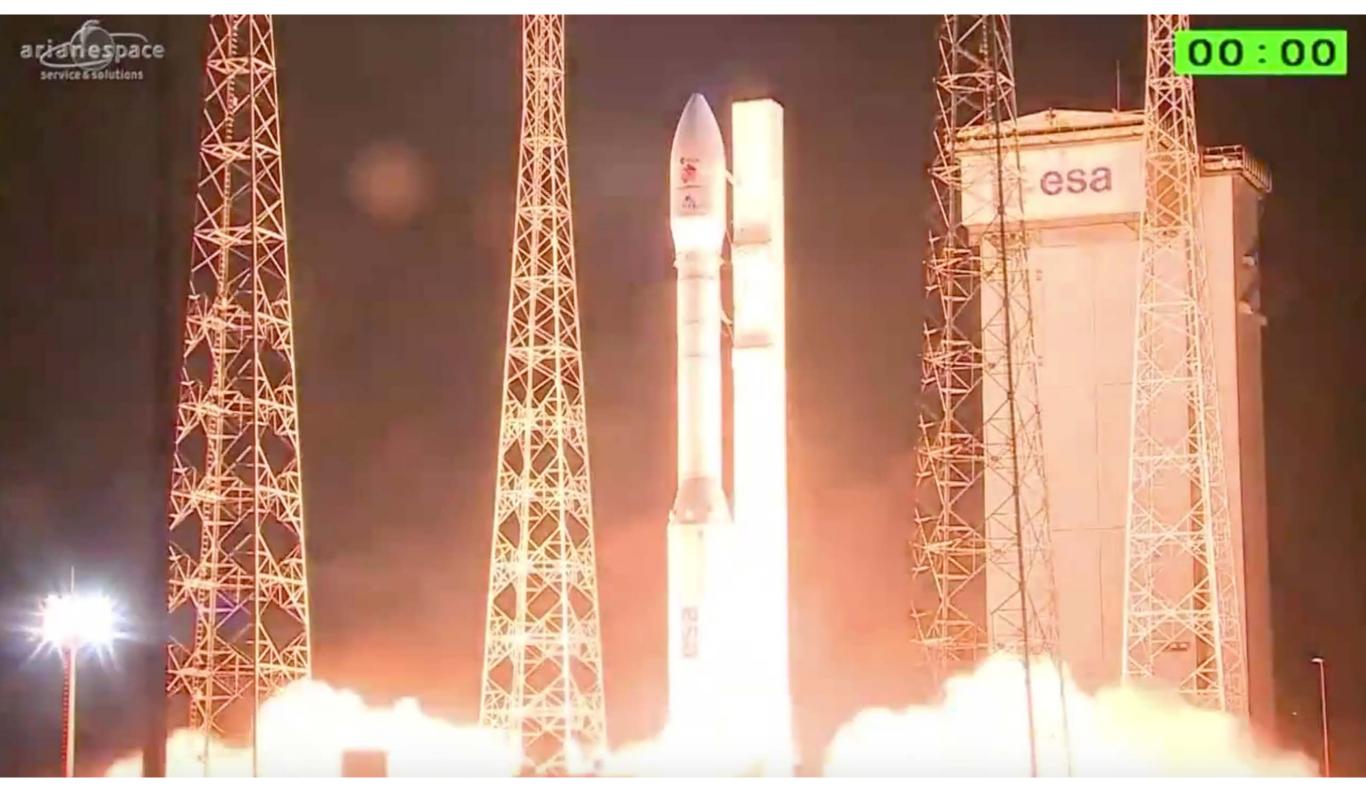






2015-12-03 01:04:00 — Kourou, French Guiana





Current Status

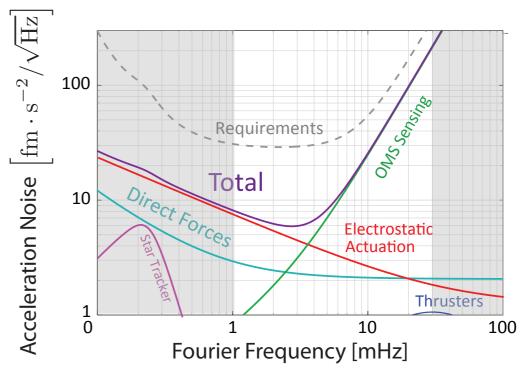
- LTP Science Operations Week 3
- Philosophy
 - take it slow
 - understand system
 - gradually introduce more aggressive experiments
- Hope to release intermediate results at some point during LTP operations
- Keep up-to-date

http://www.cosmos.esa.int/web/lisa-pathfinder http://lisapathfinder.org/





LTP Science Team Members working at ESOC in Darmstadt, Germany



Pre-flight noise breakdown estimate for LTP

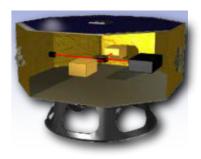


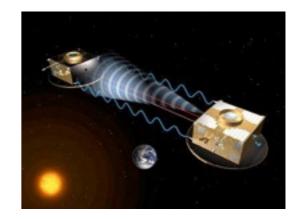


History of LPF

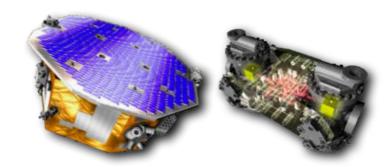


- 1998: ELITE (European LIsa TEchnology) proposed
 - Homodyne interferometer
 - Launch date 2002
- 2000: ELITE proposed as SMART-2 (Small Missions for Advanced Research in Technology)
 - Two spacecraft, three payloads
 - LISA Pathfinder (ESA), Darwin Pathfinder (ESA), Disturbance Reduction System (NASA)
- 2001: SMART-2 Descoped and re-named LISA Pathfinder
 - Darwin Pathfinder cancelled
 - single spacecraft, two payloads
 - LISA Technology Package (Europe) and DRS (NASA)
- 2005: DRS Descoped
 - DRS interferometer and inertial sensor removed
 - DRS control laws and thrusters will use LTP sensors



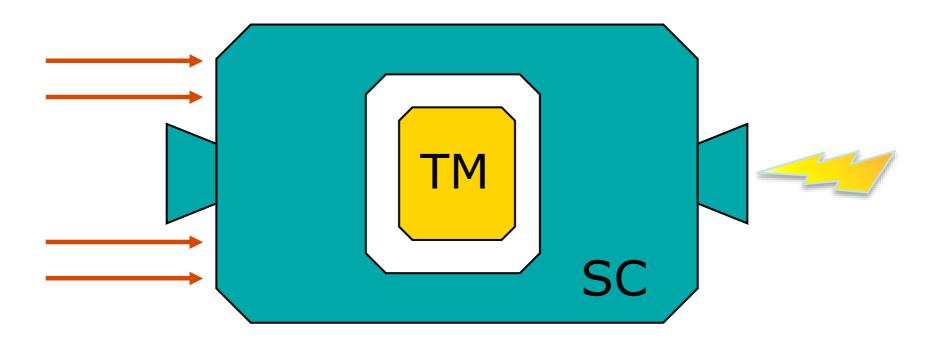








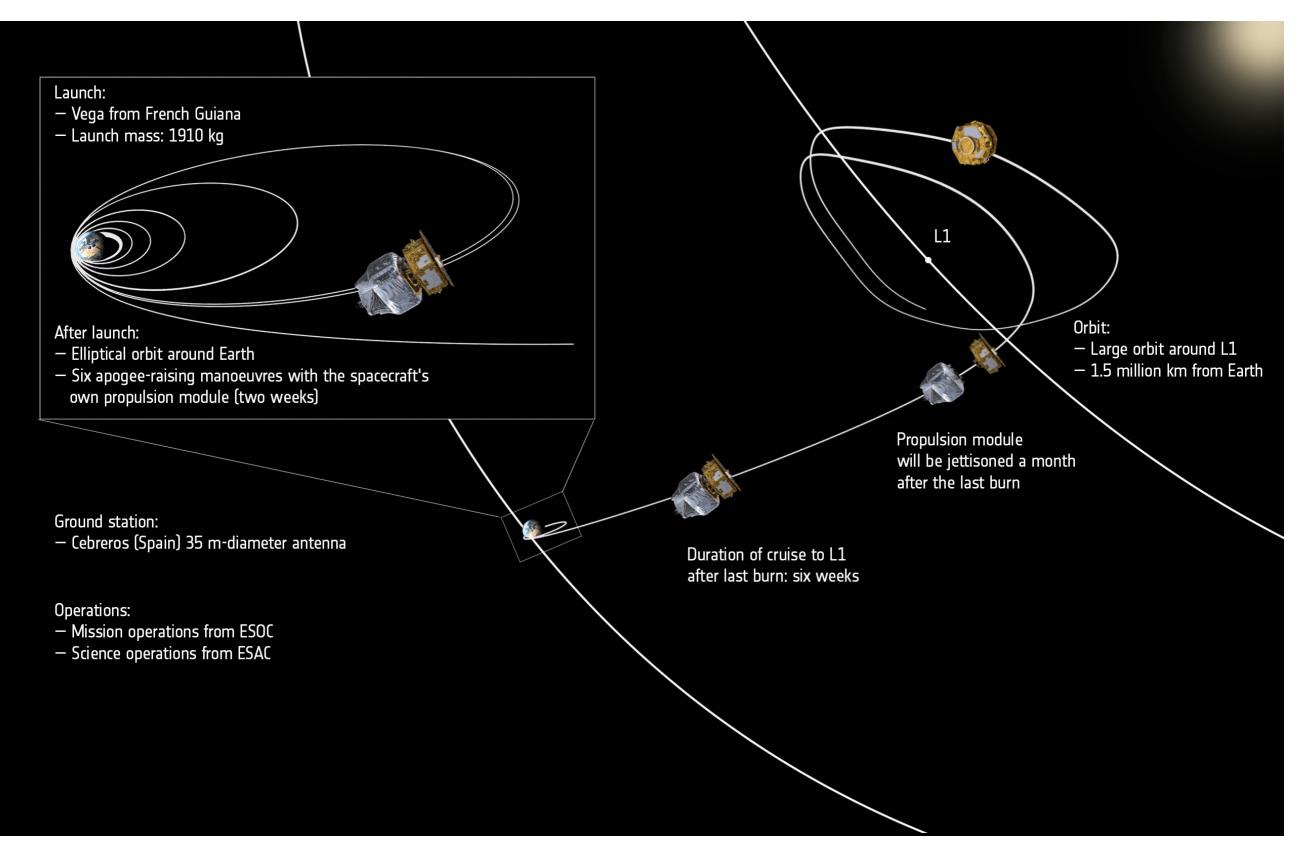




SC fires thrusters, TM remains in free fall

Mission Design





Gravitational Reference Sensor

- Test mass: 46mm cube of Au-Pt alloy (2 kg)
- surrounded by electrode housing with 3-4mm gaps
- electrodes used to sense position/ attitude and apply forces/torques
- Non-contact charge control via UV lamps
- Housed in titanium vacuum vessel
- Caged during launch, released to electrostatic suspension on orbit

I. Thorpe

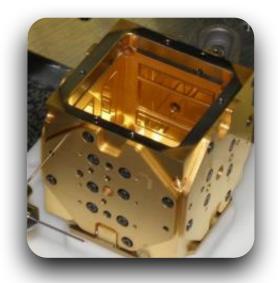
electrode housing

vacuum can



integrated electrode housings

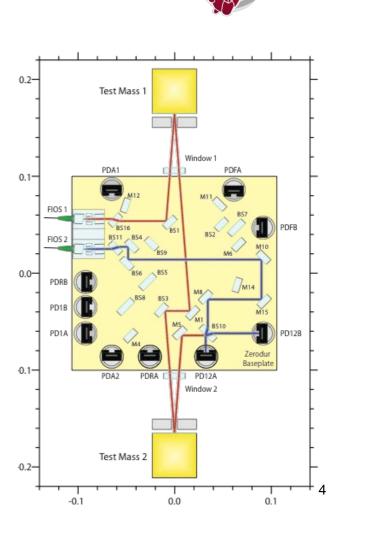
uncoated TM



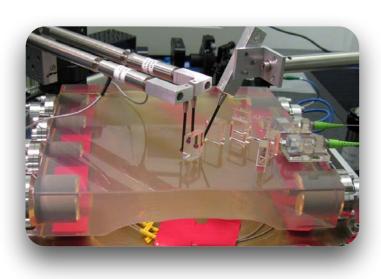


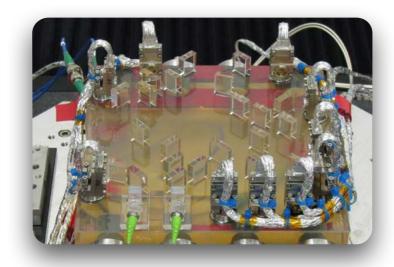
Optical Metrology System

- Four separate Mach-Zehnder interferometers to measure positions and angles
- Hydroxy-catalysis bonding to maintain alignment & provide dimensional stability



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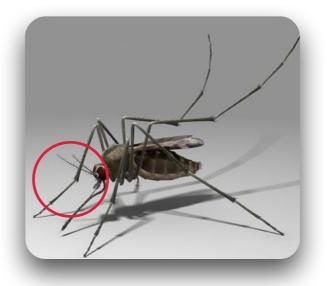




Micropropulsion Systems



- Maximum thrust ~ $30\mu N$
- Thrust precision ~ $0.1\mu N$





Colloidal MicroNewton Thruster (JPL/BUSEK)

Cold Gas Microthruster (used on GAIA)

Platform for Precision Measurement



- 2.3 m x 1.0 m
- 422kg
- magnetically clean
- precision gravitational balance
- thermally clean

