1. Heat Shield Deployment Tensegrity frame deploys heat shield and back shell.

Peak Aerothermodynamic 2. **Heating Loads**

> 3. Heat Shield **Separation**

Lightweight Multifunctional Probe for Extreme Environment Exploration and Locomotion

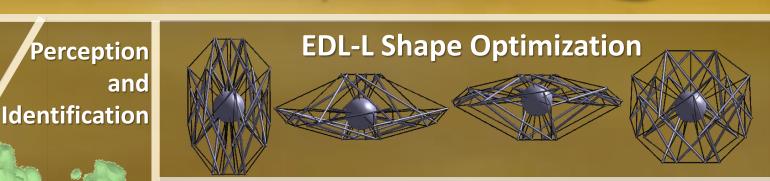
Javid Bayandor (PI), CRASH Lab, Mechanical and Aerospace Engineering, University at Buffalo – The State University of New York Jamshid Samareh (Col), NASA Langley Research Center Massimo Vespignani (Col), Jonathan Bruce (Col), NASA Ames Research Center

CRASLAB

TANDEM Mission Statement Perception

TANDEM is a unified vehicle concept coupling tensegrity robotics with a mechanically deployable semi-rigid heat shield and drag plate, developed to land in and explore the Tessera regions of Venus of scientific priority. All aspects of entry, descent, landing, and locomotion are combined into a single, multifunctional system. The TANDEM architecture is easily Venus may have had a liquid adaptable to other water ocean and habitable exploration missions surface temperatures until

Prototype Development

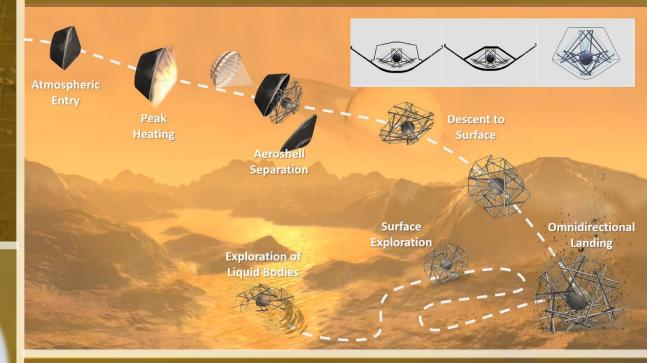


University at Buffalo

The State University of New York

NIAC Phase II

Alternative Mission Concept: Titan Rideshare



Controller Trained with Neuroevolution

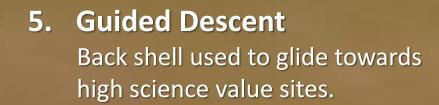
4. Analysis of **Atmospheric Gases**

CFD Analysis

Impact FE Analysis

Impact Orientation

Mapping



ENTRY

on the surface of Venus. LANDING

about 715 million years ago.

DESCENT

Freefall to Surface TANDEM is designed to withstand impact terminal velocity.

7. Omnidirectional Landing TANDEM protects the payload at all orientations of impact.

> 8. Surface Locomotion Actuation of the cables causes TANDEM to roll.

Exploration of High Science Value Sites TANDEM perceives its environment and navigates to high science value features such as lava flows and tesserae.

LOCOMOTION

Tesserae are highly deformed

represent the oldest material

geologic features which

Acknowledgements The NASA Innovative and Advanced Concepts (NIAC) Program and the NASA Space Technology Mission Directorate (STMD) are highly acknowledged for their support.

References lournal of Spacecraft and **Rockets TANDEM Report** Venus images courtesy of NASA

Dr. Javid Bayandor – CRASH Lab Director, Project Lead, Principal Investigator Dr. Jamshid Samareh – Project Co-Investigator, Institutional PI Dr. Massimo Vespignani – Project Co-Investigator, Institutional PI **Dr. Jonathan Bruce – Project Co-Investigator** Louis Rizzo – Robotics and Artificial Intelligence Lead Nicholas Deitrich – Dynamics and Controls Specialist Pradeep Vaghela – Perception, Identification, Syst. Training Specialist **Thomas Kunkel – Robotics and Simulation Specialist** Dr. Kevin Schroeder – Tensegrity Robotics Specialist Trinity Blackman – Hot Temp. Electronics, Instrumentation Specialist Alexandra Nordmann – Fluid Dynamics Modeling Specialist Ahsan Khan – Impact and Structural Analysis Specialist Jacob Bicknell – Tensegrity Optimization Specialist Madison Ciccarella – Hot Temperature Materials Specialist Joshua Cook – Locomotion and Machine Learning Specialist Karen Mae Baldonado - Future Missions and Entry Systems Specialist Jared Mcmahon – Configurations and Structural Modeling Specialist **Robert Wilder – Videography and Special Effects Lead**